Arduino Pro Mini 328 - 5V/16MHz

Overview

The Arduino Pro is a microcontroller board based on the ATmega168 (datasheet) or ATmega328 (datasheet). The Pro comes in both 3.3V / 8 MHz and 5V / 16 MHz versions. It has 14 digital input/output pins (of which 6 can be used as PWM outputs), 6 analog inputs, a battery power jack, a power switch, a reset button, and holes for mounting a power jack, an ICSP header, and pin headers. A six pin header can be connected to an FTDI cable or Sparkfun breakout board to provide USB power and communication to the board.

The Arduino Pro is intended for semi-permanent installation in objects or exhibitions. The board comes without pre-mounted headers, allowing the use of various types of connectors or direct soldering of wires. The pin layout is compatible with Arduino shields. The 3.3V versions of the Pro can be powered with a battery.

The Arduino Pro was designed and manufactured by SparkFun Electronics.

Schematic & Reference Design

EAGLE files: arduino-pro-reference-design.zip

Schematic: Arduino-Pro-schematic.pdf

Summary

<table>
<thead>
<tr>
<th>Specification</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Microcontroller</td>
<td>ATmega168 or ATmega328</td>
</tr>
<tr>
<td>Operating Voltage</td>
<td>3.3V or 5V</td>
</tr>
<tr>
<td>Input Voltage</td>
<td>3.35 -12 V (3.3V versions) or 5 - 12 V (5V versions)</td>
</tr>
<tr>
<td>Digital I/O Pins</td>
<td>14 (of which 6 provide PWM output)</td>
</tr>
<tr>
<td>Analog Input Pins</td>
<td>6</td>
</tr>
<tr>
<td>DC Current per I/O Pin</td>
<td>40 mA</td>
</tr>
<tr>
<td>Flash Memory</td>
<td>16 KB (ATmega168) or 32KB (ATmega328) of which 2 KB used by bootloader</td>
</tr>
<tr>
<td>SRAM</td>
<td>1 KB (ATmega168) or 2 KB (ATmega328)</td>
</tr>
<tr>
<td>EEPROM</td>
<td>512 bytes (ATmega168) or 1 KB (ATmega328)</td>
</tr>
</tbody>
</table>
Clock Speed

8 MHz (3.3V versions) or 16 MHz (5V versions)

Power

The Arduino Pro can be powered via the USB header, with a battery, or with an external power supply. The battery power jack is a JST header. A power jack for an external supply can be soldered to the board.

The power pins are as follows:

- **VIN.** The voltage supplied to the board from a battery or the DC power jack (according to the position of the switch). You can supply voltage through this pin, or, if supplying voltage via a battery or DC power supply, access it through this pin.
- **VCC.** The regulated power supply on the board. This comes from the battery or DC power supply via the regulator, or from the USB-to-TTL Serial convertor.
- **GND.** Ground pins.

Memory

The ATmega168 has 16 KB of flash memory for storing code (of which 2 KB is used for the bootloader). It has 1 KB of SRAM and 512 bytes of EEPROM (which can be read and written with the [EEPROM library](https://www.arduino.cc/en/Reference/EEPROM)). The ATmega328 has 32 KB of flash, 2 KB of SRAM, and 1 KB of EEPROM.

Input and Output

Each of the 14 digital pins on the Pro can be used as an input or output, using `pinMode()`, `digitalWrite()`, and `digitalRead()` functions. They operate at 3.3 volts. Each pin can provide or receive a maximum of 40 mA and has an internal pull-up resistor (disconnected by default) of 20-50 kOhms. In addition, some pins have specialized functions:

- **Serial: 0 (RX) and 1 (TX).** Used to receive (RX) and transmit (TX) TTL serial data. These pins are connected to the TX-0 and RX-1 pins of the six pin header.
- **External Interrupts: 2 and 3.** These pins can be configured to trigger an interrupt on a low value, a rising or falling edge, or a change in value. See the `attachInterrupt()` function for details.
- **PWM: 3, 5, 6, 9, 10, and 11.** Provide 8-bit PWM output with the `analogWrite()` function.
- **SPI: 10 (SS), 11 (MOSI), 12 (MISO), 13 (SCK).** These pins support SPI communication, which, although provided by the underlying hardware, is not currently included in the Arduino language.
- **LED: 13.** There is a built-in LED connected to digital pin 13. When the pin is HIGH value, the LED is on, when the pin is LOW, it's off.

The Pro has 6 analog inputs, each of which provide 10 bits of resolution (i.e. 1024 different values). By default they measure from ground to VCC, though it is possible to change the upper end of their range using the AREF pin and some low-level code. Additionally, some pins have specialized functionality:

- **I²C: 4 (SDA) and 5 (SCL).** Support I²C (TWI) communication using the [Wire library](https://www.arduino.cc/en/Reference/Wire).

There are a couple of other pins on the board:

- **AREF.** Reference voltage for the analog inputs. Used with `analogReference()`.
- **Reset.** Bring this line LOW to reset the microcontroller. Typically used to add a reset button to shields which block the one on the board.

See also the [mapping between Arduino pins and ATmega168 ports](https://www.arduino.cc/en/Reference/PinMapping).

Communication

The Arduino Pro has a number of facilities for communicating with a computer, another Arduino, or other microcontrollers. The ATmega168 and ATmega328 provide UART TTL serial communication, which is available on digital pins 0 (RX) and 1 (TX). The Arduino software includes a serial monitor which allows simple textual data to be sent to and from the Arduino board via a USB connection.
A SoftwareSerial library allows for serial communication on any of the Pro's digital pins.

The ATmega168 and ATmega328 also support I2C (TWI) and SPI communication. The Arduino software includes a Wire library to simplify use of the I2C bus; see the documentation for details. To use the SPI communication, please see the ATmega168 or ATmega328 datasheet.

**Programming**

The Arduino Pro can be programmed with the Arduino software (download). For details, see the reference and tutorials.

The ATmega168 or ATmega328 on the Arduino Pro comes preburned with a bootloader that allows you to upload new code to it without the use of an external hardware programmer. It communicates using the original STK500 protocol (reference, C header files).

You can also bypass the bootloader and program the ATmega168 or ATmega328 through the ICSP (In-Circuit Serial Programming) header; see these instructions for details.

**Automatic (Software) Reset**

Rather than requiring a physical press of the reset button before an upload, the Arduino Pro is designed in a way that allows it to be reset by software running on a connected computer. One of the pins on the six-pin header is connected to the reset line of the ATmega168 or ATmega328 via a 100 nanofarad capacitor. This pin connects to one of the hardware flow control lines of the USB-to-serial convertor connected to the header: RTS when using an FTDI cable, DTR when using the Sparkfun breakout board. When this line is asserted (taken low), the reset line drops long enough to reset the chip. The Arduino software uses this capability to allow you to upload code by simply pressing the upload button in the Arduino environment. This means that the bootloader can have a shorter timeout, as the lowering of the reset line can be well-coordinated with the start of the upload.

This setup has other implications. When the Pro is connected to either a computer running Mac OS X or Linux, it resets each time a connection is made to it from software (via USB). For the following half-second or so, the bootloader is running on the Pro. While it is programmed to ignore malformed data (i.e. anything besides an upload of new code), it will intercept the first few bytes of data sent to the board after a connection is opened. If a sketch running on the board receives one-time configuration or other data when it first starts, make sure that the software with which it communicates waits a second after opening the connection and before sending this data.

**Physical Characteristics**

The maximum length and width of the Pro PCB are 2.05 and 2.10 inches respectively, with the six pin header and power switch extending slightly beyond the edges. Four screw holes allow the board to be attached to a surface or case. Note that the distance between digital pins 7 and 8 is 160 mil (0.16”), not an even multiple of the 100 mil spacing of the other pins.