

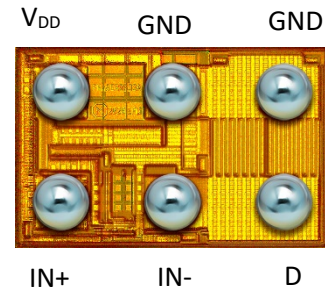
## 40 Volt, 10 Amp Peak, High-Frequency, Integrated Laser Driver

### Description

The EPC21603 is a laser driver that is controlled using LVDS logic at high frequencies of up to 100 MHz to modulate laser driving currents of up to 10 Amps. Full driver integration is achieved using EPC's proprietary GaN IC technology.

Wafer level chip-scale packaging is used resulting in a BGA package that measures only 1.5 mm x 1 mm x 0.68 mm. The BGA package has low inductance and lays out very well with the laser system.

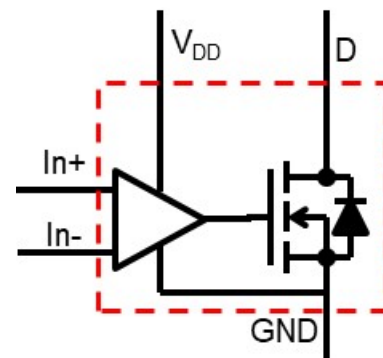
The EPC21603 uses a 5 V logic supply and is capable of interfacing to digital controllers. It can switch at frequencies exceeding 100 MHz.



1.5 mm x 1 mm, 0.5 mm pitch  
Bump side view

### Features

- $V_{\text{Laser}}$  operating range up to 30 V
- 10 Amp peak current
- Switching frequency greater than 100 MHz
- Voltage switching time less than 500 ps
- 5 V nominal logic power supply
- LVDS logic compatible input control
- 2 ns minimum input pulse width
- 2.9 ns delay time from input to output

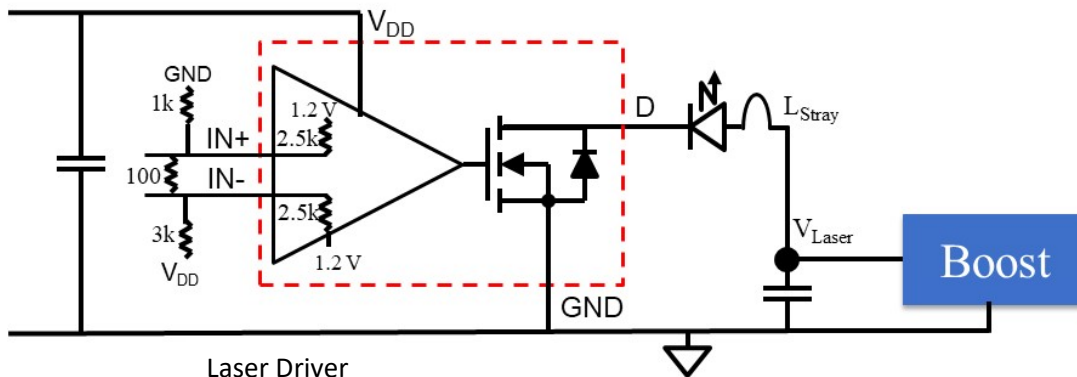


Functional Block Diagram

### Applications

- Time of flight measurement
  - Gesture recognition
  - Gaming
  - Driver monitoring
  - Robotic vision
  - Vacuum cleaners
  - Industrial safety
  - Machine vision
- ToF module using VCSEL laser for camera modules, laptops and smart phones

## Typical Connection Diagram



## Absolute Maximum Ratings

Absolute maximum ratings indicate sustained limits beyond which damage to the device may occur. All voltage parameters are absolute voltages referenced to GND unless indicated otherwise.

Symbol	Definition	Min	Max	Units
$V_D$	Drain Voltage		40	V
$V_{DD}$	Low Side Supply Voltage ( $V_{DD}$ to GND)	-0.3	5.5	V
IN	Logic Input	-0.3	5	V
$I_D$	Average Drain Current		1.7	A
$T_J$	Junction Temperature	-40	150	°C
$T_{STG}$	Storage Temperature	-40	150	°C

## ESD Ratings

(Testing performed at EAG Lab. Need to get the relevant JEDEC specs for ESD ratings)

Symbol	Definition	Min	Units
HBM	Human-body model	+/-1000	V
CDM	Charged-device model	+/-500	V

## Thermal Characteristics

$R_{\theta JA}$  is determined with the device mounted on one square inch of copper pad, single layer 2 oz copper on FR4 board.

Symbol	Definition	Typ	Units
$R_{\theta JC}$	Thermal Resistance, Junction to Case	TBD	°C/W
$R_{\theta JB}$	Thermal Resistance, Junction to Board	TBD	°C/W

$R_{\theta JA}$	Thermal Resistance, Junction to Ambient	TBD	°C/W
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## Recommended Operating Conditions

For proper operation, the device should be used within the recommended conditions. All voltage parameters are absolute voltages referenced to GND unless indicated otherwise.

Symbol	Definition	Min	Typ	Max	Units
$V_{Laser}$	Input Voltage ( $V_{IN}$ to GND)	10		30	V
$V_{DD}$	Logic Supply Voltage		5		V

## Truth Table

IN	Laser
$IN+ \leq IN-$	Off
$IN+ > IN-$	On

## Electrical Characteristics

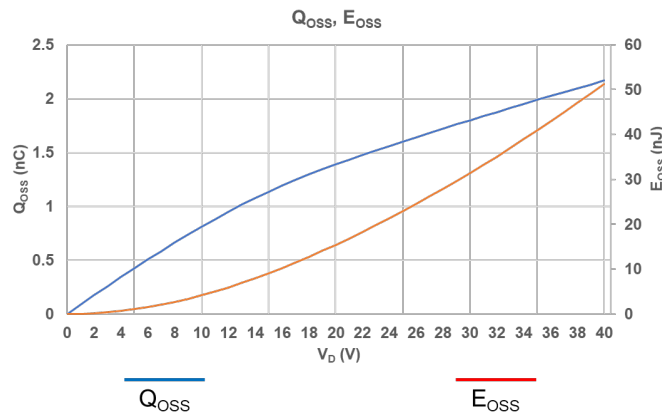
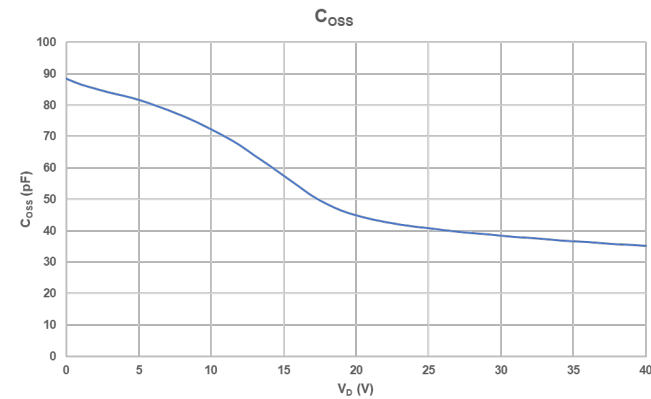
All ratings at  $T_J = 25\text{ }^\circ\text{C}$ .  $V_{Laser} = 15\text{ V}$ ,  $I_D = 5\text{ A}$ ,  $V_{IL} = 0\text{ V}$ ,  $V_{IH} = 3.3\text{ V}$ ,  $V_{DD} = 5\text{ V}$ ,  $R_D = 100\text{ }\Omega$  unless indicated otherwise.

Symbol	Definition	Min	Typ	Max	Units
<b>Operating Power Supply, <math>V_{DD}</math></b>					
$I_{DD(Off)}$	$V_{DD}$ Quiescent current with laser driver off		10.5	12.5	mA
$I_{DD(30\text{ MHz})}$	Operating current off $V_{DD}$		47	58	mA
<b>Input Pins</b>					
$V_{ITH+}$	Positive-going differential input voltage threshold, $T_J = -40\text{ }^\circ\text{C}$ to $150\text{ }^\circ\text{C}$			100	mV
$V_{ITH-}$	Negative-going differential input voltage threshold, $T_J = -40\text{ }^\circ\text{C}$ to $150\text{ }^\circ\text{C}$	-100			mV
$R_C$	Common-mode input resistance to 1.2 V		2.5		k $\Omega$
<b>Power Stage</b>					
$R_{DS(on)}$	Drain to Source Resistance		40.5	54.0	m $\Omega$
$I_{D(peak)}$	Peak Laser Drive Current Capability	10			A
$C_{OSS}$	$V_{DS} = 20\text{ V}$		45		pF
$Q_{OSS}$	$V_{DS} = 20\text{ V}$		1.4		nC
$E_{OSS}$	$V_{DS} = 20\text{ V}$		15		nJ

Dynamic Characteristics					
$t_{D(on)}$	Turn on delay time		3.5	4.5	ns
$t_F$	Drain fall time		0.41	0.6	ns
$t_{D(off)}$	Turn off delay time		3.1	4.0	ns
$t_R$	Drain rise time *		0.32	0.5	ns
$t_{dPW}$	Pulse width distortion	-0.7	-0.4	-0.2	ns
$t_{in(min(on))}$	Minimum input pulse width		2.5		ns
$t_{On(Max)}$	Maximum on time		500		ns
$t_{Off(Max)}$	Maximum off time $V_D < 10$ V		100		$\mu$ s

### Pinout Description

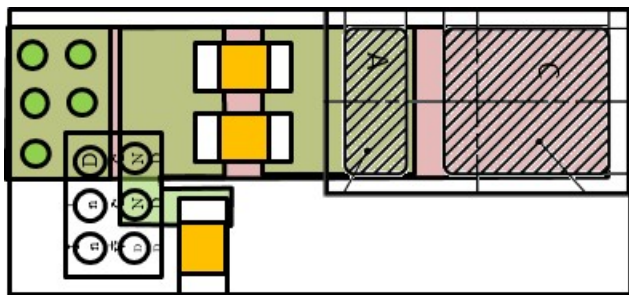
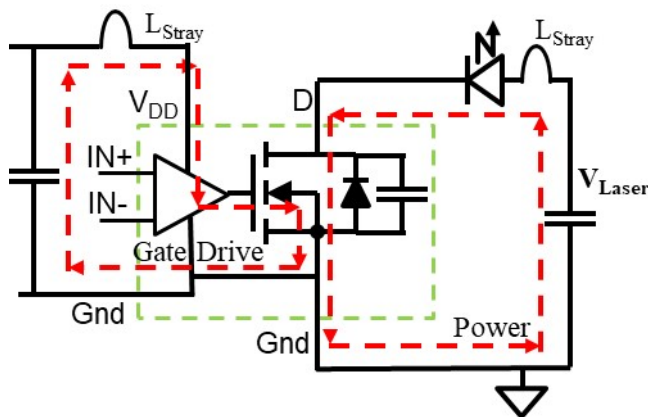
Pin	Description
$V_{DD}$	Input Voltage Supply (Decouple to GND with small, low inductance capacitor)
In+	Differential (LVDS) non-inverting output
In-	Differential (LVDS) inverting output
D	Power Drain
GND	Power and Signal Ground



## Application Information

**Layout and decoupling:** Minimizing inductance in both power and gate drive loops is critical. The power loop is primary, and gate drive loop secondary. Short, wide traces are required, and returning in the second layer, using a thin dielectric will cancel much of the inductance. Using multiple ceramic capacitors in parallel will reduce stray inductance and impedance in the power loop. Use high quality NPO or COG capacitors for both power and gate drive. This will increase effective capacitance as capacitors with lower quality materials will lose much more capacitance with voltage. Recommended layout is shown below. Component recommendations for power and gate drive decoupling capacitors are shown in the [demonstration board](#) quick start guide.

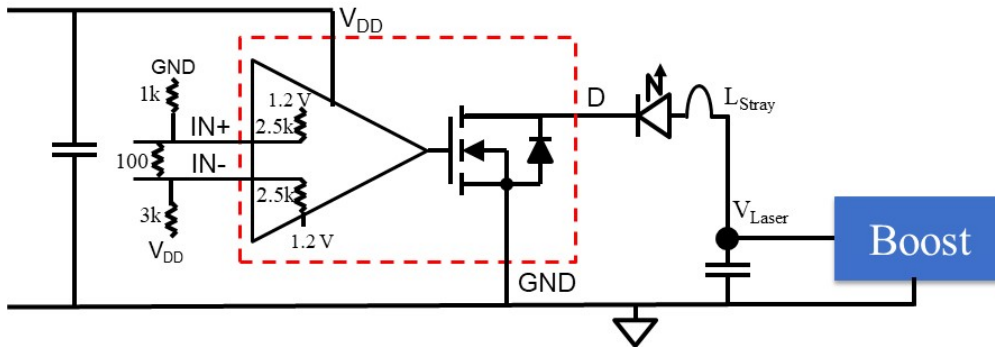
Turn off current is limited by the energy of the power loop stray inductance transferring to the  $C_{OSS}$  of the power FET of the laser driver.  $E_{OSS}$  versus  $V_{DS}$  curve is in the datasheet.



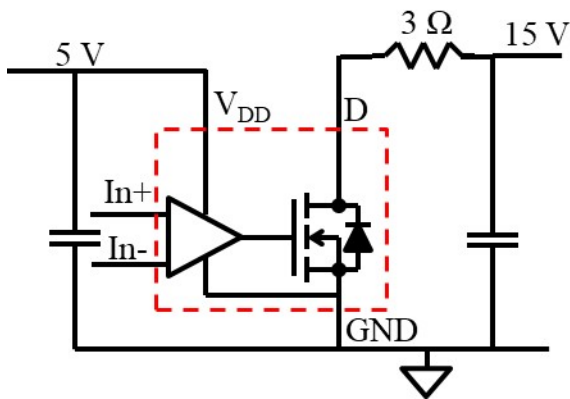
Cathode to drain connection on second conductor layer.

**Start up:**  $V_{DD}$  should be applied before the laser voltage. For applications where the laser voltage is below 10 V, it may take a few pulses before the pulse width stabilizes. For correct measurement, it may be necessary to ignore the first few pulses.

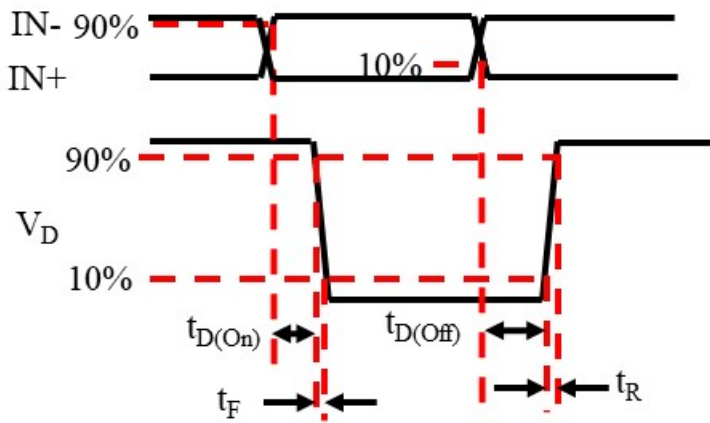
Input logic: LVDS inputs are used with each input internally pulled to 1.2 V with 2.5 kΩ . For safety IN+ should be pulled to ground with 1 kΩ and IN- should be pulled to V<sub>DD</sub> with 3 kΩ.



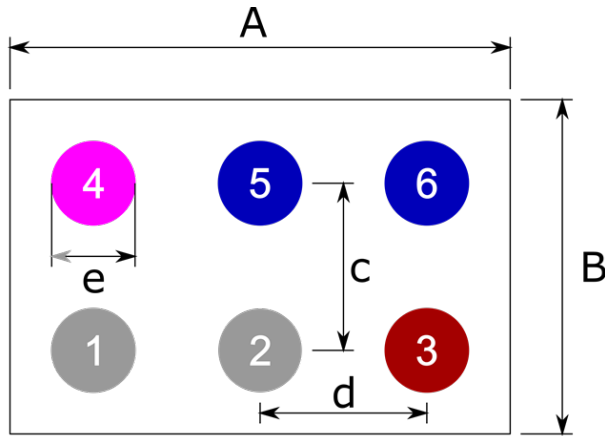
### Parameter Measurement Test Circuits



### Parameter Measurement Definitions



**Die Outline (solder bump view)**



DIM	MICROMETERS		
	MIN	Nominal	MAX
A	1420	1450	1480
B	920	950	980
c		500	
d		500	
e	238	264	290

**Pad 1 is IN+**

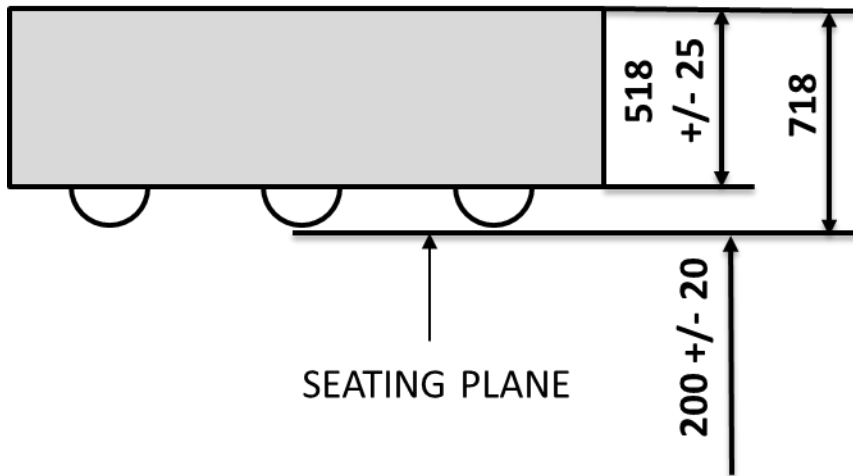
**Pad 2 is IN-**

**Pad 3 is Drain**

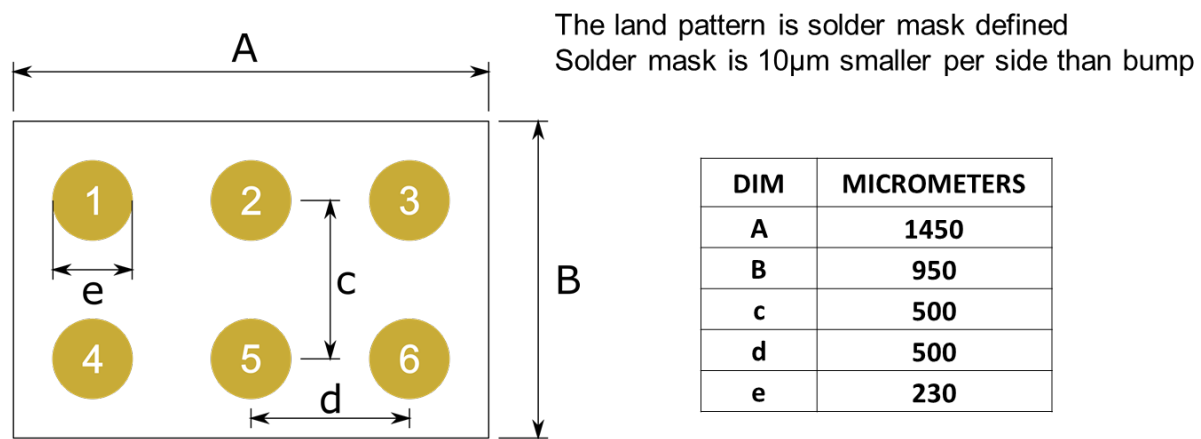
**Pad 4 is VDD**

**Pads 5, 6 are Source**

**Side View**



### Recommended Land Pattern



Pad 1 is IN+

Pad 2 is IN-

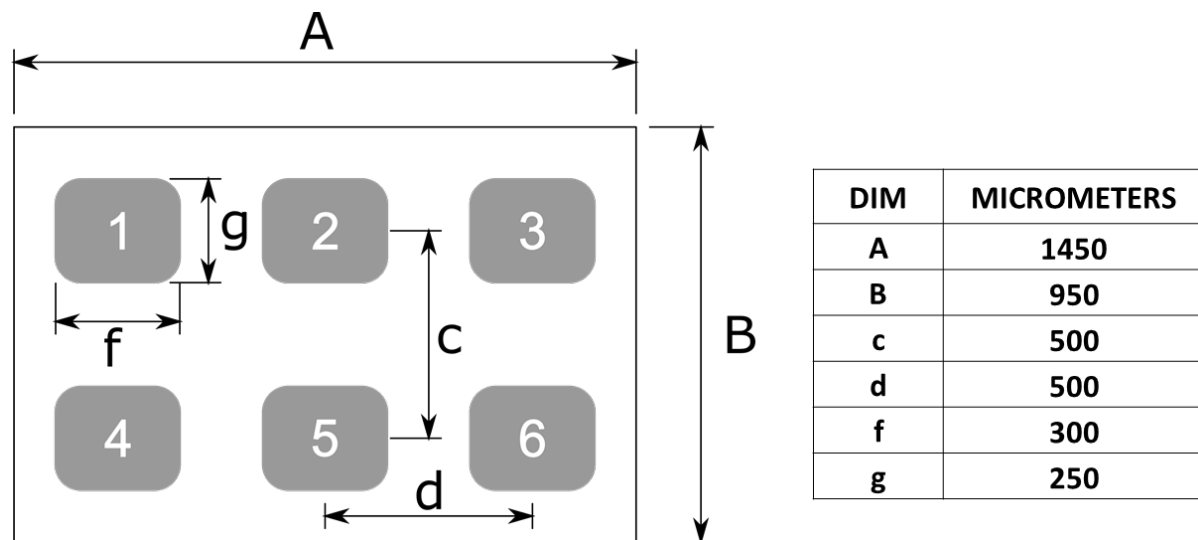
**Pad 3 is Drain**

**Pad 4 is VDD**

**Pads 5, 6 are Source**

### Recommended Stencil Drawing

(measurements in µm)



Recommended stencil should be 4mil (100 µm) thick, must be laser cut , opening per drawing.

The corner has a radius of R60

Intended for use with SAC305 Type 4 solder, reference 88.5% metals content.

Additional assembly resources are available at:

[epc-co.com/epc/DesignSupport/AssemblyBasics.aspx](http://epc-co.com/epc/DesignSupport/AssemblyBasics.aspx)

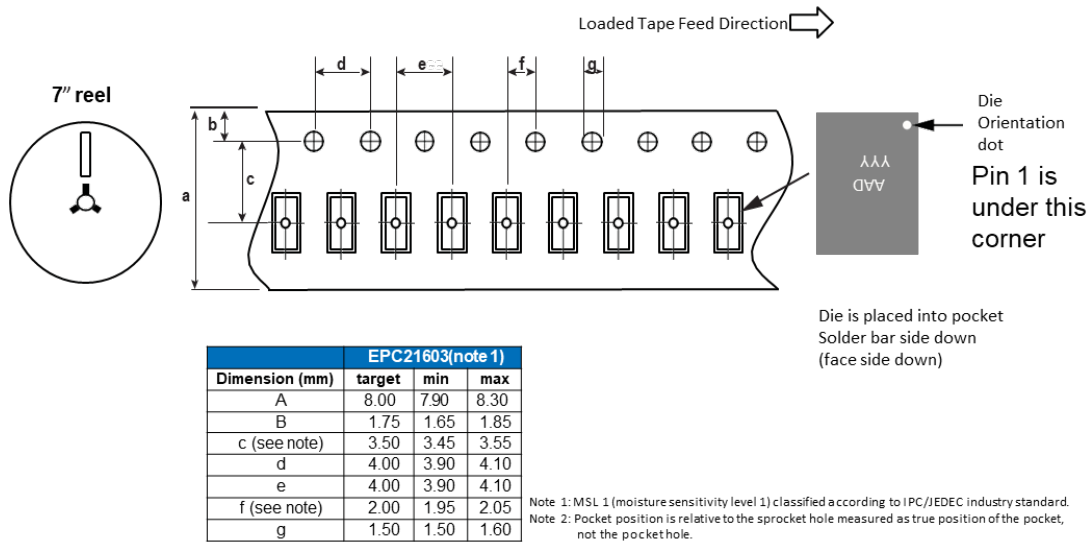


## Die Marking



## Tape and Reel Configuration

4mm pitch, 8mm wide tape on 7" reel



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